

# A few remarks on the bootstrap

For some moderately difficult statistical problems  
(a.k.a. in moderate and high dimensions)

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N. El Karoui's 3x25 birthday conference  
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# What is the bootstrap?

Bootstrap (Efron, '79): care about statistic  $\hat{\theta}_n$ ; would like to know its law. Can we do this from the data/sample we observe?

Example: sample mean; suppose we have data  $X_1, \dots, X_n$ , i.i.d,  $X_i \in \mathbb{R}$ .  $\mathbf{E}(X_i) = \mu$ ,  $\text{var}(X_i) = \sigma^2$ ; interested in

$$\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i .$$

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- Option 1: law of  $\hat{\theta}_n = \bar{X}_n$ ? Central limit theorem:

$$\sqrt{n} \frac{\bar{X}_n - \mu}{\sigma} \implies \mathcal{N}(0, 1) .$$

100 (1- $\alpha$ )%CI:  $\bar{X}_n \pm \frac{\sigma}{\sqrt{n}} z_{1-\alpha/2}$ ; t-distribution variants

- Option 2: bootstrap

# Bootstrap

More details in the case of sample mean

Idea: from the original sample, create lots of “new” datasets; this should mimick sampling mechanism which gave us  $\bar{X}_n$  from population distribution

In more detail:

- For  $b = 1, \dots, B$ , repeat:

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In particular, 95% CI could be, if  $\bar{X}_{n,(k)}$  are increasingly ordered values of  $\{\bar{X}_{n,b}^*\}_{b=1}^B$

$$(\bar{X}_{n,(2.5\%*B)}^*, \bar{X}_{n,(97.5\%*B)}^*) .$$

So called bootstrap percentile interval; simple computation shows asymptotically valid

Of course use it for much more complicated statistics

# Bootstrap

Plug-in principle etc...

$P$ : data generating distribution. Empirical distribution:

$$\hat{P}_n = \frac{1}{n} \sum_{i=1}^n \delta_{X_i}$$

Let  $\theta$  be a functional of those distributions: e.g  $\theta(P)$ : median or trimmed mean of population

Often: use  $\theta(\hat{P}_n)$  to get confidence interval/statement about  $\theta(P)$ .

Question e.g.:

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bootstrap: if  $\hat{P}_n^*$  is bootstrapped version of  $\hat{P}_n$ ,

Bootstrap law of  $[\theta(\hat{P}_n^*) - \theta(\hat{P}_n)] \simeq$  Law of  $[\theta(\hat{P}_n) - \theta(P)]$ ?

Left-hand side: we can “resample” the data to get this

Right-hand side: ideally, we would like to know it, but not accessible

# Bootstrap

More precise requirement

Suppose we are interested in random variable

$$\hat{\theta}(\hat{P}_n, P) \text{ and its law } \mathcal{L}_n(\hat{\theta}(\hat{P}_n, P))$$

E.g  $\hat{\theta}(\hat{P}_n, P) = \sqrt{n}(\mu(\hat{P}_n) - \mu(P))$

Suppose

$$\mathcal{L}_n(\hat{\theta}(\hat{P}_n, P)) \implies \mathcal{L}$$

Call  $\mathcal{L}_{n,boot}(\hat{P}_n)$  the conditional law of  $\hat{\theta}(\hat{P}_n^*, \hat{P}_n) | \hat{P}_n$

Then bootstrap works if, e.g,

$$\lim_{n \rightarrow \infty} d(\mathcal{L}_{n,boot}(\hat{P}_n), \mathcal{L}) \rightarrow 0, \text{ a.s. } X_1, \dots, X_n, \dots$$

where  $d$ : distance between probability measures; alternative:  
convergence in probability

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Example:  $X_i$  i.i.d mean  $\mu$ ,  $\text{cov}(X_i) = \Sigma$ , then conditionally on  $X_1, \dots, X_n$

$$\sqrt{n}(\bar{X}_n^* - \bar{X}_n) \implies \mathcal{N}(0, \Sigma)$$

for almost every sequence  $X_1, \dots, X_n, \dots$



# Bootstrap

Literature, variants etc...

Bootstrap: brilliant idea, **huge** impact for applied, methodological and theoretical statistics; probably one of the most widely used tool in applied statistics

Everything seems possible; no need for asymptotics. Now, beside stat practice, very useful in teaching data science and inferential ideas.

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Standard books: Davison-Hinkley (applied/theory), Hall (mostly theory), Politis-Romano-Wolf (subsampling)

And lots of variants of bootstrap (e.g m-out-of-n bootstrap (Bickel et al.), various other subsampling methods...)

Other old techniques discussed later

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One big question: when does it work?

# Bootstrap

When does it work? 1-dimensional case

Example where it does not work:  $X_i \stackrel{iid}{\sim} Unif[0, a]$ , distribution of the  $(a - \max X_i)$

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Essentially, need the function  $\theta$  to be “smooth” enough. Formal results on next slide. Informally: von Mises calculus:

$\theta$  differentiable implies: if  $\theta'(\cdot; P)$  is linear

$$\theta(\hat{P}_n) - \theta(P) \simeq \frac{1}{\sqrt{n}} \theta'(G_n; P),$$

where  $G_n = \sqrt{n}(\hat{P}_n - P)$  (Donsker thm: limit of  $G_n$  is (P-)Brownian bridge)

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Bootstrap: expand  $\theta(\hat{P}_n^*)$  around  $\theta(P)$  + linearity to get:

$$\theta(\hat{P}_n^*) - \theta(\hat{P}_n) \simeq \frac{1}{\sqrt{n}} \theta'(G_n^*; P),$$

$G_n^* = \sqrt{n}(\hat{P}_n^* - \hat{P}_n)$ ;  $G_n^*$  also has P-Brownian bridge as limit

Look at  $\theta$  as mapping from  $(D[-\infty, \infty], \|\cdot\|_\infty) \mapsto \mathbb{R}$ , where  $D$  càdlàg/rcll functions. If  $\theta$  Hadamard differentiable, i.e

$$\left| \frac{\theta(F + th_t) - \theta(F)}{t} - \theta'(h; F) \right| \rightarrow 0,$$

as  $t \rightarrow 0^+$ ,  $\forall h_t : \sup_{x \in \mathbb{R}} |h_t(x) - h(x)| \rightarrow 0$ .

$\theta'(\cdot; F)$ : continuous linear map,  $(D, \|\cdot\|_\infty) \mapsto \mathbb{R}$ .

Then bootstrap works.

Then not much need to understand fluctuation properties of

$\theta(\hat{P}_n)$ : resampling does it for us.

Often summarized as : “bootstrap works for smooth statistics”

# Plan for rest of talk

Work in the high-dimensional case: data vectors  $\{X_i\}_{i=1}^n \in \mathbb{R}^p$ ,  
 $p/n \rightarrow \kappa \in (0, 1)$

Arguments above (proximity of empirical and population distribution) fail; but what about bootstrap?

- 1 Bootstrapping (robust) regression: review
- 2 Bootstrapping regression in high-dimension: results
- 3 RM issues in bootstrap

Why  $p/n$  not close to 0?

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Why  $p/n$  not close to 0? 1) often better small sample approximations; 2) often allows comparison of methods at 1st order and not second order; so more dramatic differencing of methods - often consistent with practical knowledge 3) power series vs 1st order approximation 4) problems statistically non-trivial



# Review: How to bootstrap in regression?

Model

Motto: copy the data-generating distribution.

Model:  $Y_i \in \mathbb{R}$ ,  $X_i \in \mathbb{R}^p$ ,

$$Y_i = X_i^T \beta_0 + \epsilon_i, 1 \leq i \leq n.$$

For  $\rho$  loss function, consider

$$\hat{\beta}_\rho = \operatorname{argmin}_{\beta \in \mathbb{R}^p} \sum_{i=1}^n \rho(Y_i - X_i^T \beta).$$

Simplest question: can get CI for  $\beta_0(1)$  based on  $\hat{\beta}_\rho(1)$ ?

# Review: How to bootstrap in regression?

## Bootstrapping from residuals

Motto: copy the data-generating process.

Model:  $Y_i \in \mathbb{R}$ ,  $X_i \in \mathbb{R}^p$ ,

$$Y_i = X_i^T \beta_0 + \epsilon_i, 1 \leq i \leq n.$$

What's random?  $\epsilon_i$  in this context; they are i.i.d.

$X_i$  assumed “fixed” in this example.

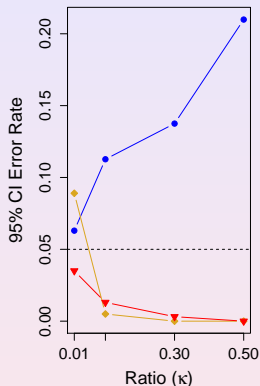
So **bootstrap from the residuals**:

- ➊ estimate  $\beta_0$  by  $\hat{\beta}_\rho$
- ➋ estimate  $\epsilon_i$  by  $e_i$ 's; typically  $e_i = Y_i - X_i^T \hat{\beta}$
- ➌ Repeat for  $b = 1, \dots, B$ 
  - ➊ Get new errors  $e_{i,b}^*$  by sampling i.i.d at random from  $\{e_i\}_{i=1}^n$
  - ➋ Get new dataset  $Y_{i,b}^* = X_i^T \hat{\beta} + e_{i,b}^*$
  - ➌ Fit this new dataset to get  $\hat{\beta}_b^*$

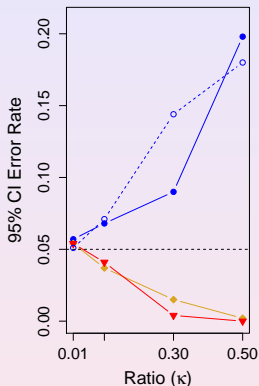
Do inference using  $\{\hat{\beta}_b^*\}_{b=1}^B$

# Bootstrapping from the residuals

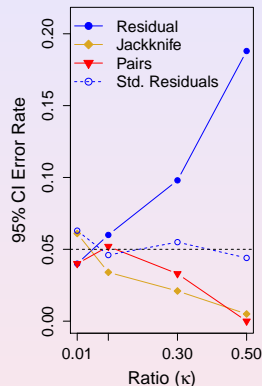
$$\epsilon_j \stackrel{iid}{\sim} \mathcal{N}(0, 1)$$



(a)  $L_1$  loss



(b) Huber loss



(c)  $L_2$  loss

**Figure: Performance of 95% confidence intervals of  $\beta_1$  :  $n = 500$ , 1,000 simulations** Residuals method is anti-conservative!

# Bootstrapping from the residuals

Understanding and fixing(?) the problem

Note: Bickel and Freedman ('83) studied high-dimensional residual bootstrap for least-squares; showed that residuals did not have the right distribution. Mammen ('89) for robust regression when  $p^2/n \rightarrow 0$

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Of course, if  $e = \{e_i\}_{i=1}^n$  are residuals,

$$e = (\text{Id} - X(X^T X)^{-1} X^T) \epsilon \triangleq (\text{Id} - H) \epsilon .$$

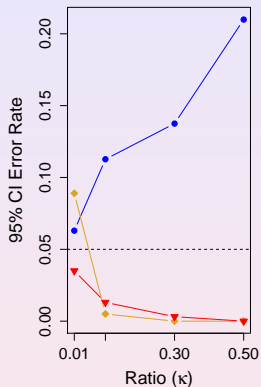
So suggestion for resampling (see e.g Davison-Hinkley '97, many others): use

$$\tilde{e}_i = \frac{e_i}{\sqrt{1 - H_{i,i}}} , H = X(X^T X)^{-1} X^T$$

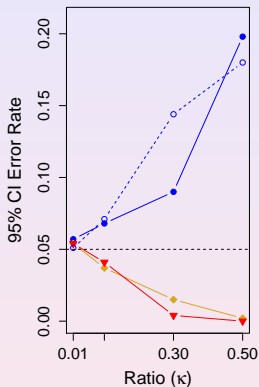
In low-dimension, this correction is minimal; in high-d, Gaussian case,  $H_{i,i} \simeq 1 - \frac{p}{n}$ : non-negligible correction

# Bootstrapping from the standardized residuals

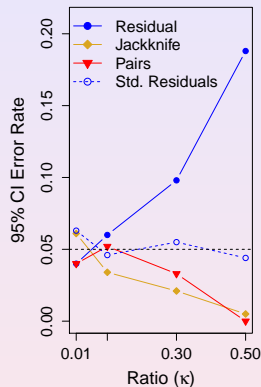
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(a)  $L_1$  loss



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**Figure: Performance of 95% confidence intervals of  $\beta_1$  :  $n = 500$ , 1,000 simulations** Method works for  $L_2$ ; standardization for Huber (see McKean et al. '93) not effective.

# Bootstrapping from the residuals

Can we understand situation? Reminders

Recall  $M$ -estimation problem above. Suppose  $p/n \rightarrow \kappa \in (0, 1)$ . For simplicity of statement,  $X_i$  i.i.d with mean-0 i.i.d entries with many moments.

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## Theorem

*Under regularity conditions on  $\{\epsilon_j\}$  and  $\rho$  (convex),  $\|\hat{\beta}_\rho - \beta_0\|_2$  is asymptotically deterministic. Call  $r_\rho(\kappa)$  its limit and  $\hat{z}_\epsilon = \epsilon + r_\rho(\kappa)Z$ , where  $Z \sim \mathcal{N}(0, 1)$ , independent of  $\epsilon$ . For  $c$  deterministic, we have*

$$\begin{cases} \mathbf{E} ([prox(c\rho)]'(\hat{z}_\epsilon)) &= 1 - \kappa, \\ \kappa r_\rho^2(\kappa) &= \mathbf{E} ([\hat{z}_\epsilon - prox(c\rho)(\hat{z}_\epsilon)]^2) . \end{cases}$$

By definition, (Moreau '65), for convex function  $f$ ,

$$prox(f)(x) = \operatorname{argmin}_y \left( f(y) + \frac{1}{2}(x - y)^2 \right) .$$



# Bootstrapping from residuals

On the residuals: reminders

Call  $e_i = Y_i - \hat{\beta}_\rho^T X_i$ , the  $i$ -th residual. In the asymptotic limit,

$$e_i \stackrel{\mathcal{L}}{=} \text{prox}(c\rho)(\epsilon_i + r_\rho(\kappa)Z_i), Z_i \sim \mathcal{N}(0, 1) \perp\!\!\!\perp \epsilon_i$$

where  $Z_i \sim \mathcal{N}(0, 1)$  independent of  $\epsilon_i$ .

- ❶ if  $\rho(x) = x^2/2$ ,  $\text{prox}(c\rho)[x] = \frac{x}{1+c}$ ; hence, here  $\frac{1}{1+c} = 1 - \kappa$
- ❷ if  $\rho(x) = |x|$ ,  $\text{prox}(c\rho)[x] = \text{sgn}(x)(|x| - c)_+$

Comments:

- ❶ even in LS case,  $e_i$ 's do not have the right marginal distribution. However, only  $\text{var}(e_i)$  matters then... Hence, simple scaling works, though usual interpretation misleading/wrong

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- ② For other loss functions, clear that performance depends on more than a few moments, hence problems
- ③ Bickel-Freedman, '83, for OLS - answered a slightly different question

# Bootstrapping from the residuals

Further comments

- 1 Advocated for a long-time even in robust regression (e.g. Shorack '81): clearly problematic here
- 2 Many methods suggested in low-dimension to improve second order accuracy: see e.g. Koenker ('05), Parzen et al. ('94), De Angelis et al. ('93), McKean et al. ('93); outside of  $L_2$ , these methods did not improve our numerical results
- 3 So question: can we do better?

# Bootstrapping from residuals

A couple ideas

Recall that in robust regression, asymptotically, in setting considered here:

$$Y_i - X_i^T \hat{\beta} = \mathbf{e}_i \stackrel{\mathcal{L}}{=} \text{prox}(c\rho)(\epsilon_i + r_\rho(\kappa)Z_i), Z_i \sim \mathcal{N}(0, 1) \perp\!\!\!\perp \epsilon_i$$

$\text{prox}(c\rho)$  problematic: so instead, use as basis of work

$$\begin{aligned}\tilde{\mathbf{e}}_{i,(i)} &= Y_i - X_i^T \hat{\beta}_{(i)} = \epsilon_i + X_i^T (\beta_0 - \hat{\beta}_{(i)}), \text{ because} \\ \mathbf{e}_i &= \text{prox}(c\rho)(\tilde{\mathbf{e}}_{i,(i)}).\end{aligned}$$

where  $\hat{\beta}_{(i)}$  is leave- $i$ -th-observation out estimate. Remarks:

- Stochastic structure of  $\tilde{\mathbf{e}}_{i,(i)}$  comparatively simpler than that of  $\mathbf{e}_i$

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where  $\hat{\beta}_{(i)}$  is leave- $i$ -th-observation out estimate. Remarks:

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- Problem 1 with  $\tilde{\mathbf{e}}_{i,(i)}$ : excess variance compared to  $\epsilon_i$

# Bootstrapping from residuals

A couple ideas

Recall that in robust regression, asymptotically, in setting considered here:

$$Y_i - X_i^T \hat{\beta} = \mathbf{e}_i \stackrel{\mathcal{L}}{=} \text{prox}(c\rho)(\epsilon_i + r_\rho(\kappa)Z_i), Z_i \sim \mathcal{N}(0, 1) \perp\!\!\!\perp \epsilon_i$$

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- Problem 1 with  $\tilde{\mathbf{e}}_{i,(i)}$ : excess variance compared to  $\epsilon_i$
- Problem 2 with  $\tilde{\mathbf{e}}_{i,(i)}$ : extra “Gaussian” component

# Bootstrapping the residuals

## Approach 1: scaling predicted errors

Idea: resample from  $\tilde{e}_{i,(i)}$  but properly scale them. Need at least right variance...

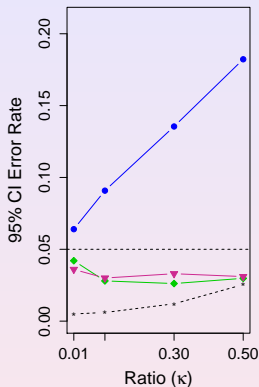
How to do so?

- 1 Estimate  $\sigma^2(\epsilon)$  using least squares: easy to get consistent estimator in high-dimension for that
- 2 Easy to get estimate of  $\|(\beta_0 - \hat{\beta}_{(i)})\|$  then.
- 3 Normalize  $e_{i,(i)}$  to  $\tilde{e}_{i,(i)}$  so variance of the latter is  $\hat{\sigma}(\epsilon)$ .
- 4 Use  $\tilde{e}_{i,(i)}$  in bootstrap resampling

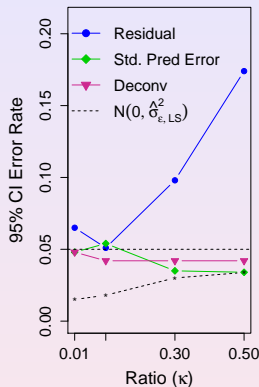


# Bootstrapping the residuals

Approach 1: scaling predicted errors;  $\epsilon_j \overset{iid}{\sim}$  double exponential



(a)  $L_1$  loss



(b) Huber loss

**Figure: Bootstrap based on predicted errors:** We plotted the error rate of 95% confidence intervals for alternative bootstrap methods: bootstrapping from standardized predicted errors (blue) and from deconvolution of predicted error (magenta).

# Further bootstraps

Conclusion about bootstrapping residuals:

- 1 Need to be careful - in general not accurate/can fail
- 2 Anti-conservative in general: CI do not cover the true value with the probability we want
- 3 Appears possible to fix to a certain/large extent the problems

# Another type of bootstrap

Resampling the pairs

Will now discuss another type of bootstrap: **pairs-resampling**

# Another type of bootstrap

## Resampling the pairs

Will now discuss another type of bootstrap: **pairs-resampling**

In standard books, this is the technique that is favored in general.

Idea:

- For  $b = 1, \dots, B$ , sample with replacement from  $(X_i, Y_i)_{i=1}^n$ .
- Get new dataset  $(X_{i,b}^*, Y_{i,b}^*)_{i=1}^n$
- Fit model to this new dataset to get  $\{\hat{\beta}_b^*\}_{b=1}^B$

Do inference using  $\{\hat{\beta}_b^*\}_{b=1}^B$

# Pairs bootstrap

## More details

Note that, if  $w_{i,b}^*$  is number of times  $(X_i, Y_i)$  appears in  $b$ -th boot sample:

$$\hat{\beta}_b^* = \operatorname{argmin}_{\beta \in \mathbb{R}^p} \sum_{i=1}^n w_{i,b}^* \rho(Y_i - X_i^T \beta) .$$

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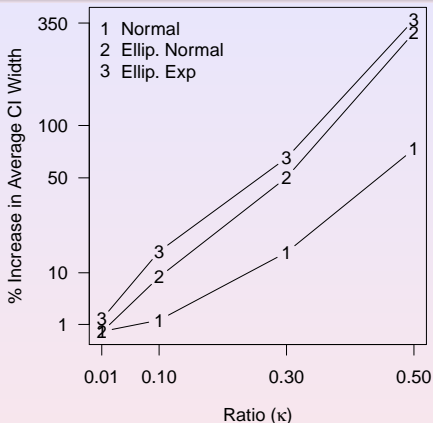
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- 5 Note however that reweighting also affects  $\epsilon_i$ 's

# Pairs bootstrap

How does it fare?



**Figure: Comparison of width of 95% confidence intervals of  $\beta_1$  for  $L_2$  loss:** y-axis is the percent increase of the average confidence interval width based on simulation ( $n = 500$ ), as compared to the average for the standard confidence interval based on normal theory in  $L_2$ ; the percent increase is plotted against the ratio  $\kappa = p/n$  (x-axis)

# Pairs bootstrapping

Some theory

## Theorem

*Weights  $(w_i)_{i=1}^n$  be i.i.d.,  $\mathbf{E}(w_i) = 1$ ; enough moments and bounded away from 0.  $X_i \stackrel{iid}{\sim} \mathcal{N}(0, \text{Id}_p)$ ;  $v$  : deterministic unit vector.*

*Suppose  $\hat{\beta}$  is obtained by solving a least-squares problem - linear model holds;  $\text{var}(\epsilon_i) = \sigma_\epsilon^2$*

*If  $\lim p/n = \kappa < 1$  then asymptotically as  $n \rightarrow \infty$*

$$p \mathbf{E} \left( \text{var} \left( v^T \hat{\beta}_w^* \right) \right) \rightarrow \sigma_\epsilon^2 \left[ \kappa \frac{1}{1 - \kappa - \mathbf{E} \left( \frac{1}{(1 + cw_i)^2} \right)} - \frac{1}{1 - \kappa} \right],$$

*$c$  : unique solution of*

$$\mathbf{E} \left( \frac{1}{1 + cw_i} \right) = 1 - \kappa.$$

# Pairs bootstrapping

A comment

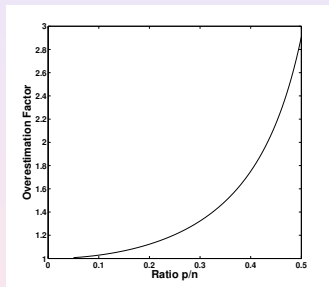
Note that of course in setup above,

$$\text{pvar} \left( \mathbf{v}^T \hat{\beta} \right) \rightarrow \sigma_{\epsilon}^2 \frac{\kappa}{1 - \kappa}$$

- 1 Pairs-bootstrap does not get the right variance
- 2 Confidence intervals are too wide: method is **conservative** (covers the truth more often than it should)
- 3 Ratio  $\mathbf{E} \left( \text{var} \left( \mathbf{v}^T \hat{\beta}_w^* \right) \right) / \text{var} \left( \mathbf{v}^T \hat{\beta} \right)$  does not depend on  $\text{cov}(X_i) = \Sigma$  - results true for any  $\Sigma$
- 4 Suggest weight corrections (not discussed because of time constraints)

# Pairs bootstrapping

## Numerics

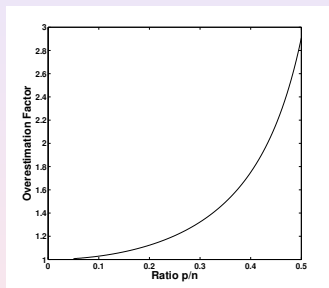


(a)  $L_2$  (Theoretical)

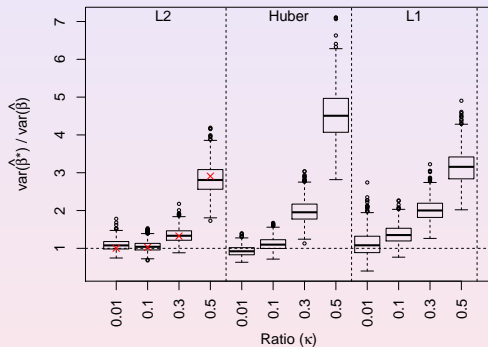
**Figure:** Factor by which standard pairs bootstrap over-estimates the variance: Gaussian design, Gaussian errors

# Pairs bootstrapping

## Numerics



(a)  $L_2$  (Theoretical)



(b) All (Simulated)

**Figure: Factor by which standard pairs bootstrap over-estimates the variance:** Gaussian design, Gaussian errors

# Beyond regression problems

Are these issues limited to the simple setting of regression?



## Another type of statistics: eigenvalues of covariance matrices

# Sample covariance matrices and their eigenvalues

Recall if data is  $X_i$ ,

$$\hat{\Sigma} = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})(X_i - \bar{X})^T.$$

Bootstrap quite widely used to assess fluctuation behavior of eigenvalues of sample covariance matrices. See Beran and Srivastava ('85), Eaton and Tyler ('91)

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Bootstrapping eigenvalues currently used in a number of fields (see e.g several papers in British Journal of Psychology '07)

Now question: is that true if  $p/n \rightarrow c \neq 0$ ?

Recall

Theorem (Johnstone ('01))

If  $X_i$  are i.i.d  $\mathcal{N}(0, \text{Id}_p)$ , then as  $p/n \rightarrow \gamma \in (0, \infty)$

$$n^{2/3} \frac{\lambda_{\max}(\hat{\Sigma}) - (1 + \sqrt{p/n})^2}{\sigma_{n,p}} \Rightarrow TW_1 .$$

Further results: phase transition at  $\lambda_1(\Sigma) = 1 + \sqrt{p/n}$  (BBP, '04); general  $\Sigma$  case (N<sub>2</sub>EK, '05; Lee and Schnelli '13). Much work since then.

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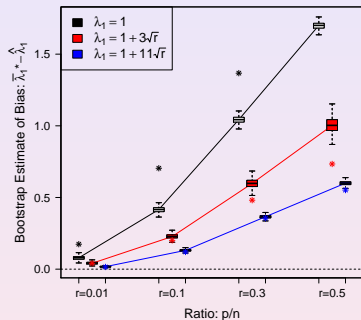
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Also classic work (Marcenko-Pastur ('67), Wachter ('78)) about empirical spectral distribution of eigenvalues

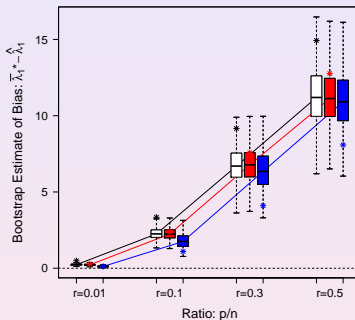


# Eigenvalues

Numerics: bias



(a)  $Z \sim \text{Normal}$

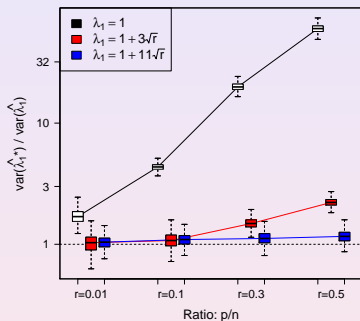


(b)  $Z \sim \text{Ellip. Exp}$

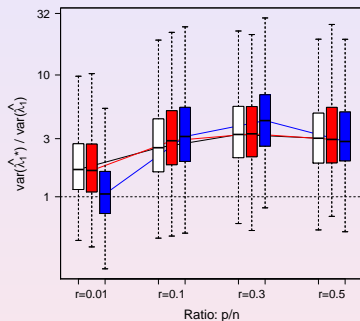
**Figure: Bias of Largest Bootstrap Eigenvalue,  $n=1,000$ :** Plotted are boxplots of the difference of the average bootstrap value of  $\lambda_1$  over 999 bootstrap samples, minus the estimate  $\hat{\lambda}_1$  over 1000 simulations;  $\bar{\lambda}_1^* - \hat{\lambda}_1$  is also the standard bootstrap estimate of bias.

# Eigenvalues

Numerics: variance



(a)  $Z \sim \text{Normal}$

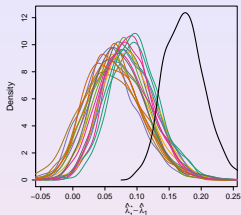


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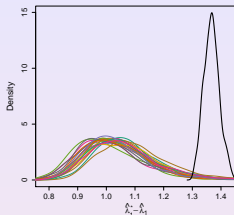
**Figure: Ratio of Bootstrap Estimate of Variance to True Variance for Largest Eigenvalue,  $n=1,000$ :** Plotted are boxplots of the bootstrap estimate of variance ( $B = 999$ ) as a ratio of the true variance of  $\hat{\lambda}_1$ ; boxplots represent the bootstrap estimate of variance

# Eigenvalues

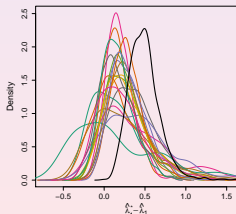
Numerics: distribution in null case



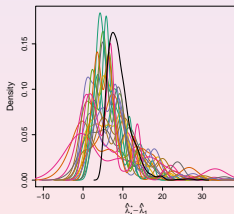
(a)  $Z \sim \text{Normal}$ ,  $r=0.01$



(b)  $Z \sim \text{Normal}$ ,  $r=0.3$



(c)  $Z \sim \text{Ellip. Exp}$ ,  
 $r=0.01$



(d)  $Z \sim \text{Ellip. Exp}$ ,  
 $r=0.3$

# Eigenvalues

Theory: skipped in interest of time

- Simple theory for well separated eigenvalues
- Possible to do theory of spectral distribution of eigenvalues:  
Results are negative: bootstrapped Stieltjes transform concentrates but around the “wrong” Stieltjes transform.
- Can be used (with a few more refined tools) to understand bootstrap bias

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Bootstrap :

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- Seems bootstrap genuinely perturbation-analytic method
- Large  $n, p$  theory seems to capture some phenomena observed in practice - may lead to a practically informative theory.

# Bon anniversaire!



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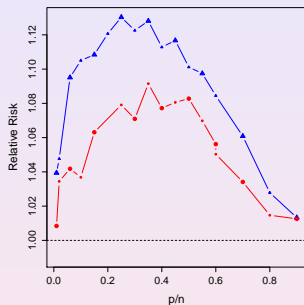


# Bon anniversaire!



# Robust regression estimator

Impact of error distribution

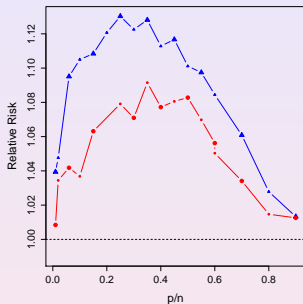


(a)

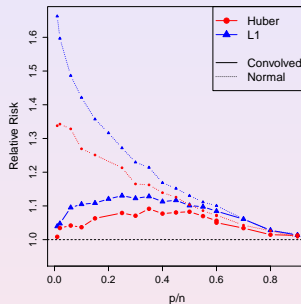
**Figure:** Solid line: Relative Risk of  $\hat{\beta}$  for scaled predicted errors vs original errors - population version

# Robust regression estimator

## Impact of error distribution



(a)



(b)

**Figure:** Solid line: Relative Risk of  $\hat{\beta}$  for scaled predicted errors vs original errors - population version Dotted line: using  $\eta_i \stackrel{iid}{\sim} \mathcal{N}(0, \sigma_\epsilon^2)$