

Hedging Distributions with BSDE

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Let X be an \mathcal{F}_T -measurable r.v. on $(\Omega, \mathcal{F}, \mathbf{P})$.

- ① $F_X(\cdot)$: the probability distribution function of X ;
- ② $F_X^{-1}(\cdot)$: the inverse of $F_X(\cdot)$; also called the quantile function of X ;
- ③ $\Phi(\cdot)$: the standard normal distribution;
- ④ $X \sim \mu$: X is an \mathcal{F}_T -measurable random variable following the distribution μ ;
- ⑤ $\mathbb{E}[f(\mu)] : = \int f(x)d\mu(x)$ for a probability distribution function μ and any function f ;
- ⑥ $D_t X$: the Malliavin derivative of any random variable or vector X for $t \in [0, T]$.

Problem setting

Consider a driver g and an \mathcal{F}_T measurable random variable X , such that the following BSDE

$$\begin{cases} dY_t = g(t, Y_t, Z_t)dt + Z'_t dB_t, \\ Y_T = X, \end{cases} \quad (1)$$

admits a unique adapted solution $(Y(\cdot), Z(\cdot))$. For example, $X \in L^2(\mathcal{F}_T)$ and g is a Lipschitz function.

We call Y_0 the g -expectation of X , denoted by $\mathbb{E}_g[X]$.

Important Bibliography

[EPQ97] EL KAROUI, N., PENG, S. G., AND QUENEZ, M. C.
(1997) Backward stochastic differential equations in finance
Mathematical Finance, Vol. 7, pp. 1-71

Definition

A distribution μ is called hedgeable (or replicable) via BSDE (1) (or equivalently, its driver g), if there exists $(Y(\cdot), Z(\cdot))$ following the (1) with $Y_T \sim \mu$.

Efficient Hedging Problem

If μ is a hedgeable distribution via a driver g , the problem of efficient hedging μ via the driver g is

$$\inf_{X \sim \mu} \mathbb{E}_g[X]. \quad (2)$$

- We only consider square-integrable distributions μ , that is, probability distributions satisfying $\mathbb{E}[\mu^2] < \infty$. In such case, clearly we have $X \in L^2(\mathcal{F}_T)$ whenever $X \sim \mu$.
- We call a random variable X^* an optimal solution, if $X^* \sim \mu$ and $\mathbb{E}_g[X^*] = \inf_{X \sim \mu} \mathbb{E}_g[X]$.

Lemma 1

If $g(t, y, z) = r_t y + \theta_t z + \delta_t$, with r, θ bounded and δ is square integrable, then

$$\mathbb{E}_g[X] = \mathbb{E}[\rho_T X] - \int_0^T \mathbb{E}[\delta_s \rho_s] ds.$$

where $\rho_t = \exp\left(-\int_0^t (r_s + \frac{1}{2}\|\theta_s\|^2) ds - \int_0^t \theta'_s dB_s\right)$.

Hardy-Littlewood Inequality

If a square integrable r.v. η is atomless, then

$$\inf_{X \sim \mu} \mathbb{E}[\eta X] = \mathbb{E}[\eta X^*] = \int_0^1 F_\eta^{-1}(1-p) \mu^{-1}(p) dp,$$

where $X^* = \mu^{-1}(1 - F_\eta(\eta))$ is the unique random variable $\sim \mu$ that is anti-comonotonic with η .

Theorem.

With same the driver $g(t, y, z) = r_t y + \theta'_t z + \delta_t$ as above, the efficient Hedging problem has the optimal value

$$\inf_{X \sim \mu} \mathbb{E}_g[X] = \int_0^1 F_{\rho_T}^{-1}(1-p) \mu^{-1}(p) dp - \int_0^T \mathbb{E}[\delta_s \rho_s] ds,$$

where ρ_t is defined by Lemma 1, and $X^* = \mu^{-1}(1 - F_{\rho_T}(\rho_T))$ is its unique optimal solution, provided that ρ_T is atomless.

Remark

If both r_t and θ_t are determinist processes, then ρ_T is atomless.

First experiment

Concave Case as in [EPQ97]

Suppose g is concave in (y, z) . Let

$$\hat{g}(t, \alpha, \beta) = \sup_{y, z} (g(t, y, z) - \alpha y - \beta' z)$$

Then

$$g(t, y, z) = \inf_{\alpha, \beta} (\hat{g}(t, \alpha, \beta) + \alpha y + \beta' z).$$

Let $h(t, y, z; \alpha, \beta) = \hat{g}(t, \alpha, \beta) + \alpha y + \beta' z$. By [EPQ97]

$$\mathbb{E}_g[X] = \sup_{(\alpha, \beta) \in \mathcal{A}} \mathbb{E}_{h(\alpha, \beta)}[X],$$

with $(\alpha, \beta) \in \mathcal{A} := \{\mathbb{E} \int_0^T g^2(t, \alpha, \beta) dt < \infty\}$. So that

$$\inf_{X \sim \mu} \mathbb{E}_g[X] = \inf_{X \sim \mu} \sup_{(\alpha, \beta) \in \mathcal{A}} \mathbb{E}_h[X] \geq \sup_{(\alpha, \beta) \in \mathcal{A}} \inf_{X \sim \mu} \mathbb{E}_h[X].$$

Second Experiment.

We consider a market when deposit and loan rates are not same

- loan rate R_t and deposit rate r_t such that $R_t \geq r_t$
- σ_t be the an invertible volatility matrix,
- θ_t be the risk premium of the market, i.e., $\theta_t = \sigma_t^{-1}(b_t - r_t \mathbf{1})$,
- All above processes are deterministic and uniformly bounded.

For a small investor, his (self-financing) wealth process Y_t with portfolio π to hedge a random payoff X follows a BSDE:

$$\begin{cases} dY_t = (r_t Y_t + \theta_t' \sigma_t' \pi_t - (R_t - r_t)(Y_t - \mathbf{1}' \pi_t)^-) dt + \pi_t' \sigma_t dB_t, \\ Y_T = X. \end{cases}$$

The driver is $g(t, y, z) = r_t y + \theta_t' z - (R_t - r_t)(y - \mathbf{1}'(\sigma_t')^{-1} z)^-$.

Theorem [Comparison Principle]

Let $(Y^i(\cdot), Z^i(\cdot))$ be the solutions of the BSDE (1) with parameters (g_i, X_i) , $i = 1, 2$, respectively. If

$$X_1 \geq X_2, \quad g_1(t, Y_t^1, Z_t^1) \leq g_2(t, Y_t^1, Z_t^1), \quad \forall 0 \leq t \leq T;$$

or

$$X_1 \geq X_2, \quad g_1(t, Y_t^2, Z_t^2) \leq g_2(t, Y_t^2, Z_t^2), \quad \forall 0 \leq t \leq T;$$

then $Y_t^1 \geq Y_t^2$ for all $0 \leq t \leq T$.

- $\mathbf{D}_{1,2}$ be the set of random variables or vectors ξ , which admits a Malliavin derivative $D_t\xi$ for $t \in [0, T]$, such that

$$\|\xi\|_{1,2} = \mathbb{E}\|\xi\|^2 + \int_0^T \|D_s\xi\|^2 ds < +\infty.$$

By Malliavin calculus + Comparison principle,

Theorem. [EPQ97]

$Y(\cdot)$ follows BSDE with $X \in \mathbf{D}_{1,2}$.

- If $\mathbf{1}'(\sigma'_t)^{-1}D_tX \geq X$, $dP \times dt$ -a.s., then $Y_t \equiv \bar{Y}_t$, where $(\bar{Y}(\cdot), \bar{Z}(\cdot))$ is the solution of the linear BSDE

$$\begin{cases} d\bar{Y}_t = (R_t\bar{Y}_t + (\theta_s - (R_s - r_s)\sigma_s^{-1}\mathbf{1})\bar{Z}_t)dt + \bar{Z}_t' dB_t, \\ \bar{Y}_T = X. \end{cases}$$

Continue...

- In fact, $\bar{Y}_t \equiv \bar{\rho}_t^{-1} \mathbb{E}[\bar{\rho}_T X | \mathcal{F}_t]$, where

$$\begin{aligned} \bar{\rho}_t = \exp \bigg(& - \int_0^t (R_s + \tfrac{1}{2} \|\theta_s - (R_s - r_s) \sigma_s^{-1} \mathbf{1}\|^2) ds \\ & - \int_0^t (\theta_s - (R_s - r_s) \sigma_s^{-1} \mathbf{1})' dB_s \bigg). \end{aligned} \quad (3)$$

- If $\mathbf{1}'(\sigma'_t)^{-1} D_t X \leq X$, $dP \times dt$ -a.s., then $Y_t \equiv \tilde{Y}_t$, where $(\tilde{Y}(\cdot), \tilde{Z}(\cdot))$ is the solution of the linear BSDE

$$\begin{cases} d\tilde{Y}_t = (r_t \tilde{Y}_t + \theta'_t \tilde{Z}_t) dt + \tilde{Z}'_t dB_t, \\ \tilde{Y}_T = X. \end{cases}$$

In fact, $\tilde{Y}_t \equiv \rho_t^{-1} \mathbb{E}[\rho_T X | \mathcal{F}_t]$.

Proposition.

With same assumptions,

$$\inf_{X \sim \mu} \mathbb{E}_g[X] \leq \min \left\{ \mathbb{E}[\rho_T \tilde{X}], \mathbb{E}[\bar{\rho}_T \bar{X}] \right\},$$

where ρ_t and $\bar{\rho}_t$ are defined as above, $\tilde{X} = \mu^{-1}(1 - F_{\rho_T}(\rho_T))$ and $\bar{X} = \mu^{-1}(1 - F_{\bar{\rho}_T}(\bar{\rho}_T))$. Moreover,

- if $\mathbf{1}'\sigma_t^{-1}D_t\tilde{X} \leq \tilde{X}$, $dP \times dt$ -a.s., then

$$\text{Case I : } \inf_{X \sim \mu} \mathbb{E}_g = \mathbb{E}_g[\tilde{X}] = \mathbb{E}[\rho_T \tilde{X}],$$

- if $\mathbf{1}'\sigma_t^{-1}D_t\bar{X} \geq \bar{X}$, $dP \times dt$ -a.s., then

$$\text{Case II : } \inf_{X \sim \mu} \mathbb{E}_g[X] = \mathbb{E}_g[\bar{X}] = \mathbb{E}[\bar{\rho}_T \bar{X}],$$

Theorem.

For all $0 \leq t \leq T$

- If $\mu(0-) = 0$ and $\mathbf{1}'(\sigma'_t)^{-1}\theta_t \leq 0$, then Case I holds.
- If $\mu(0) = 1$ and $\mathbf{1}'(\sigma'_t)^{-1}(\theta_t - (R_t - r_t)\sigma_t^{-1}\mathbf{1}) \geq 0$, then Case II holds.
- Let $f(x) = \mu^{-1}(1 - F_{\rho_T}(x))$ and $c = \sup_{t \in [0, T]} \mathbf{1}'(\sigma'_t)^{-1}\theta_t$, if

$$f(x) \geq -cx f_x(s), x > 0$$

then Case I holds.

Proof. Chain rule for Malliavin Calculus.

Remark.

If we take $\sigma_t = \begin{pmatrix} 4 & 0.1 \\ 0.1 & 1 \end{pmatrix}$, $\theta_t = \begin{pmatrix} 1.9 \\ 0.1 \end{pmatrix}$, then $\mathbf{1}'(\sigma'_t)^{-1}\theta_t \leq 0$. In fact

$$\begin{aligned} \mathbf{1}'(\sigma'_t)^{-1}\theta_t \leq 0 &\Leftrightarrow \mathbf{1}'(\sigma'_t\sigma_t)^{-1}(b_t - r_t) \leq 0, \\ \mathbf{1}'(\sigma'_t)^{-1}(\theta_t - (R_t - r_t)\sigma_t^{-1}\mathbf{1}) \geq 0 &\Leftrightarrow \mathbf{1}'(\sigma'_t\sigma_t)^{-1}(b_t - R_t) \geq 0. \end{aligned}$$

Special cases.

There are two important examples in theory of g -expectation:

$$g^k(z) = k|z|, g^{-k}(z) = -k|z|.$$

By comparison principle, if $g(z)$ satisfies Lipschitz condition for some constant k , then

Maybe some boundary for efficient hedging problem

$$\begin{aligned} \mathbb{E}_{g^k}[X] &\leq \mathbb{E}_g[X] \leq \mathbb{E}_{g^{-k}}[X] \\ \Rightarrow \inf_{X \sim \mu} \mathbb{E}_{g^k}[X] &\leq \inf_{X \sim \mu} \mathbb{E}_g[X] \leq \inf_{X \sim \mu} \mathbb{E}_{g^{-k}}[X] \end{aligned}$$

$$g^k(z) = -k|z|$$

Consider normal distribution $\mu = N(m, \sigma)$. For $a \geq 1$, let $\xi^a = m + \sqrt{\sigma a} B_{\frac{1}{a}} \sim N(m, \sigma)$, then

$$Z_t^{\xi^a} = \sqrt{\sigma a} 1_{\{t \leq \frac{1}{a}\}}.$$

So

$$\mathbb{E}[\xi] \leq \inf_{\xi \sim \mu} Y_0^\xi \leq \inf_{a \geq 1} Y_0^{\xi^a} = \inf_{a \geq 1} \left(\mathbb{E}[\xi] + k \sqrt{\frac{\sigma}{a}} \right) = \mathbb{E}[\xi].$$

Proposition

If $\mathbb{E}[\mu^2] < +\infty$, then

$$\inf_{X \sim \mu} \mathbb{E}_{g^{-k}}[X] = \mathbb{E}[\mu].$$

Sketch of Proof.

For a distribution μ , set $X = \mu^{-1}(\Phi_T(B_T)) \sim \mu$. By non-linear Feymann-Kac formula, and scale changing of Brownian motion $X^\alpha = \mu^{-1}\left(\Phi_T\left(\sqrt{\alpha}B_{\frac{T}{\alpha}}\right)\right) \sim \mu$, for $\alpha \geq 1$, we can construct a sequence \bar{Y}_t^α , such that

$$\mathbb{E}_{g^{-k}}[X] = \bar{Y}_0^\alpha = \mathbb{E}[X] + \frac{1}{\sqrt{\alpha}} \mathbb{E}\left[\int_0^T k \left|\bar{Z}_s^\alpha\right| ds\right].$$

We can prove that \bar{Z}_s^α is uniformly square integrable, which yields

$$\inf_{X \sim \mu} \mathbb{E}_g[X] \leq \lim_{\alpha \rightarrow \infty} \bar{Y}_0^\alpha \leq \mathbb{E}[X] + \lim_{\alpha \rightarrow \infty} \frac{\sqrt{T}}{\sqrt{\alpha}} (C\mathbb{E}[X^2])^{\frac{1}{2}} = \mathbb{E}[X].$$

Obviously $\mathbb{E}_{g^{-k}}[X] \geq \mathbb{E}[X]$ by definition of g -expectaion.

Corollary

For any Lipschitz function $g(z)$, efficient hedging problem is majored by

$$\inf_{X \sim \mu} \mathbb{E}_g[X] \leq \mathbb{E}[\mu].$$

Small Generalization

Assumption

The driver $g(t, z)$ is a deterministic function of (t, z) , and satisfies

- Non-positivity: $g(t, z) \leq 0$;
- Lipschitz continuity: $|g(t, z_1) - g(t, z_2)| \leq K\|z_1 - z_2\|$, $K > 0$;
- Positive homogeneity: $g(t, \alpha z) = \alpha g(t, z)$, for any $\alpha \geq 0$.

Remark

The drivers $g(t, z)$ that satisfy assumption must be of the form

$$g(t, z) \equiv -A'_t z^+ - C'_t z^-.$$

Theorem.

If a driver g satisfies above assumptions. Then

$$\inf_{X \sim \mu} \mathbb{E}_g[X] = \mathbb{E}[\mu],$$

$$g^k(z) = k|z|$$

Consider normal distribution $\mu = N(m, \sigma)$. Let $\xi^n = m + \sqrt{\sigma a} B_{\frac{T}{a}} \sim N(m, \sigma)$, for $a \geq 1$, then

$$Z_t^{\xi^a} = \sqrt{\sigma a} 1_{\{t \leq \frac{1}{a}\}}.$$

So

$$\inf_{\xi \sim \mu} Y_0^\xi \leq \inf_{a \geq 1} Y_0^{\xi^a} = \inf_{a \geq 1} \left(\mathbb{E}[\xi] - k \sqrt{\frac{\sigma}{a}} \right) = \mathbb{E}[\xi] - k\sqrt{\sigma}.$$

Proposition.

Given a distribution μ , set $X^* = \mu^{-1}(\Phi_T(B_T)) \sim \mu$. We consider $X^\alpha = \mu^{-1}(\Phi_T(\sqrt{\alpha} B_{\frac{T}{\alpha}})) \sim \mu$, for $\alpha \geq 1$, then

$$\inf_{X \sim \mu} \mathbb{E}_{g^k}[X] \leq \inf_{\alpha} \mathbb{E}_{g^k}[X^\alpha] = \mathbb{E}_{g^k}[X^*] \leq \mathbb{E}[\mu].$$

Law-invariant g -expectation

Definition [Law-invariant g -expectation]

Given a distribution μ , we call a driver g is μ -invariant, if $\mathbb{E}_g[X]$ are the same, denoted as $\mathbb{E}_g[\mu]$ for all $X \sim \mu$. A g -expectation (or its driver g) is called law-invariant if it is μ -invariant for any square-integrable μ .

Example. Entropy measure

The driver $g(t, y, z) \equiv -\frac{1}{2}z^2$ is law-invariant. By Itô's formula

$$d e^{Y_t} = e^{Y_t} Z'_t dB_t.$$

Hence $e^{Y_0} = \mathbb{E}[e^{Y_T}] = \mathbb{E}[e^\mu]$ if $Y_T \sim \mu$. In another word, $\mathbb{E}_g[X] = \log(\mathbb{E}[e^\mu])$ for any $X \sim \mu$, which is μ -invariant.

Theorem. [when g not depending on t]

Each time-invariant driver of the form $g(t, y, z) \equiv -f(y)\|z\|^2$ is law-invariant and

$$\mathbb{E}_g[\mu] = \varphi^{-1}\left(\mathbb{E}[\varphi(\mu)]\right),$$

for any distribution μ such that the right hand side is well-defined, where

$$\varphi(x) = \int_0^x \exp\left(2 \int_0^y f(s)ds\right) dy.$$

- Experiment of g may depend on t is still ongoing.....
- As well as applications in portfolio selection problem....

Thanks you!

Happy Birthday!

福如东海
寿比南山

